Control at T1 (weight\_a) v. T2 (weight\_a) by Interested in News

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| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| Variable | Prompt and Responses | Control at T1  All  (n = 745) | Some of the time  (n = 226) | Only now and then  (n = 93) | Most of the time  (n = 352) | Hardly at all  (n = 39) | Don't know  (n = 35) | Control at T2  All  (n = 745) | Some of the time  (n = 226) | Only now and then  (n = 93) | Most of the time  (n = 352) | Hardly at all  (n = 39) | Don't know  (n = 35) | Difference  All | Some of the time | Only now and then | Most of the time | Hardly at all | Don't know |
| q1 | Things in California going in right/wrong direction | 0.440 | 0.458 | 0.338 | 0.511 | 0.077 | 0.598 | 0.426 | 0.380 | 0.323 | 0.513 | 0.262 | 0.545 | -0.013 (P = 0.324) | -0.078 (P = 0.003) | -0.014 (P = 0.418) | 0.002 (P = 0.930) | 0.184 (P = 0.006) | -0.053 (P = 0.305) |
|  | Right Direction | 43.8% | 48.1% | 31.0% | 52.5% | 18.7% | 39.6% | 24.9% | 23.0% | 15.0% | 33.4% | 15.9% | 23.1% | -19.0% | -25.1% | -16.0% | -19.1% | -2.8% | -16.5% |
|  | Wrong Direction | 41.8% | 37.2% | 44.3% | 44.7% | 57.1% | 25.6% | 31.4% | 33.0% | 31.4% | 31.0% | 38.5% | 16.9% | -10.4% | -4.2% | -12.9% | -13.7% | -18.5% | -8.7% |
|  | DK/NA | 14.3% | 14.7% | 24.7% | 2.8% | 24.2% | 34.9% | 43.7% | 44.0% | 53.6% | 35.6% | 45.6% | 60.0% | 29.4% | 29.3% | 28.9% | 32.8% | 21.4% | 25.2% |
| q2 | How accurately video describes California's future in 2050 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | In the middle | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% |
|  | Not well | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% |
|  | Well | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% |
|  | DK/NA | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% |
| q16\_r | Things in California going in right/wrong direction | 6.758 | 6.672 | 5.674 | 6.758 | 8.513 | 6.246 | 6.818 | 7.168 | 6.747 | 6.438 | 6.930 | 7.300 | 0.060 (P = 0.623) | 0.496 (P = 0.025) | 1.073 (P = 0.004) | -0.320 (P = 0.065) | -1.583 (P = 0.000) | 1.054 (P = 0.041) |
|  | In the middle | 9.9% | 7.5% | 17.3% | 9.1% | 15.2% | 4.1% | 5.7% | 4.2% | 8.5% | 4.3% | 14.5% | 2.4% | -4.2% | -3.3% | -8.8% | -4.8% | -0.7% | -1.7% |
|  | Not well | 14.2% | 15.3% | 19.6% | 14.3% | 2.9% | 12.2% | 7.4% | 5.8% | 4.6% | 12.7% | 1.3% | 2.7% | -6.8% | -9.6% | -15.0% | -1.6% | -1.6% | -9.5% |
|  | Well | 59.8% | 63.0% | 43.7% | 65.8% | 55.2% | 53.1% | 38.6% | 40.5% | 28.9% | 41.1% | 36.4% | 39.6% | -21.2% | -22.4% | -14.8% | -24.7% | -18.8% | -13.5% |
|  | DK/NA | 16.1% | 14.2% | 19.4% | 10.8% | 26.6% | 30.6% | 48.3% | 49.5% | 57.9% | 41.9% | 47.7% | 55.3% | 32.2% | 35.3% | 38.6% | 31.1% | 21.1% | 24.7% |
| q36\_r | Things in California going in right/wrong direction | 6.162 | 6.629 | 6.870 | 5.435 | 5.914 | 7.834 | 6.356 | 7.348 | 6.429 | 5.392 | 6.265 | 7.175 | 0.194 (P = 0.110) | 0.719 (P = 0.001) | -0.441 (P = 0.163) | -0.043 (P = 0.813) | 0.350 (P = 0.501) | -0.659 (P = 0.000) |
|  | In the middle | 8.3% | 4.2% | 8.2% | 15.2% | 2.5% | 3.0% | 6.6% | 4.4% | 4.9% | 11.1% | 3.4% | 3.0% | -1.7% | 0.2% | -3.3% | -4.1% | 0.9% | 0.0% |
|  | Not well | 25.5% | 22.3% | 15.1% | 32.8% | 39.2% | 7.2% | 13.0% | 7.4% | 10.8% | 21.7% | 14.1% | 0.9% | -12.5% | -15.0% | -4.3% | -11.1% | -25.1% | -6.4% |
|  | Well | 59.9% | 68.8% | 69.1% | 49.3% | 52.4% | 60.1% | 39.0% | 46.7% | 30.8% | 32.6% | 45.3% | 40.8% | -20.9% | -22.2% | -38.4% | -16.8% | -7.1% | -19.3% |
|  | DK/NA | 6.3% | 4.6% | 7.6% | 2.6% | 5.9% | 29.6% | 41.4% | 41.6% | 53.5% | 34.6% | 37.2% | 55.3% | 35.1% | 37.0% | 46.0% | 31.9% | 31.4% | 25.7% |
| q70 | Things in California going in right/wrong direction | 7.818 | 8.189 | 7.754 | 7.428 | 9.063 | 5.985 | 8.098 | 8.445 | 7.467 | 7.544 | 8.914 | 9.393 | 0.281 (P = 0.006) | 0.256 (P = 0.066) | -0.287 (P = 0.459) | 0.116 (P = 0.307) | -0.149 (P = 0.624) | 3.408 (P = 0.001) |
|  | In the middle | 6.5% | 5.3% | 13.2% | 6.5% | 1.4% | 6.0% | 2.2% | 2.2% | 0.5% | 2.3% | 5.6% | 1.1% | -4.3% | -3.1% | -12.7% | -4.3% | 4.2% | -4.8% |
|  | Not well | 13.2% | 11.1% | 10.7% | 17.8% | 2.0% | 20.1% | 6.8% | 4.9% | 6.8% | 11.7% | 1.2% | 0.0% | -6.3% | -6.2% | -3.8% | -6.1% | -0.8% | -20.1% |
|  | Well | 78.8% | 83.0% | 73.5% | 75.7% | 96.6% | 61.5% | 50.6% | 53.7% | 35.4% | 52.6% | 58.7% | 44.1% | -28.3% | -29.2% | -38.1% | -23.1% | -37.9% | -17.3% |
|  | DK/NA | 1.5% | 0.7% | 2.7% | 0.0% | 0.0% | 12.4% | 40.4% | 39.2% | 57.2% | 33.5% | 34.6% | 54.7% | 38.9% | 38.5% | 54.6% | 33.5% | 34.6% | 42.3% |
| q85 | Things in California going in right/wrong direction | 0.644 | 0.650 | 0.551 | 0.847 | 0.085 | 0.440 | 0.640 | 0.657 | 0.560 | 0.854 | 0.074 | 0.283 | -0.004 (P = 0.806) | 0.008 (P = 0.829) | 0.009 (P = 0.876) | 0.007 (P = 0.640) | -0.010 (P = 0.740) | -0.157 (P = 0.029) |
|  | Not well | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 60.8% | 61.1% | 48.2% | 66.8% | 65.4% | 49.5% | -39.2% | -38.9% | -51.8% | -33.2% | -34.6% | -50.5% |
|  | DK/NA | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 39.2% | 38.9% | 51.8% | 33.2% | 34.6% | 50.5% | 39.2% | 38.9% | 51.8% | 33.2% | 34.6% | 50.5% |
| q94 | Things in California going in right/wrong direction |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | In the middle | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% |
|  | Not well | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% |
|  | Well | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% |
|  | DK/NA | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 100.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% | 0.0% |
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